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# **Use of the NASA KSC 50-MHz ST Profiler for Operations Support to Spaceflight — Part I, Characterization of the Instrument**

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# KSC 50-MHz Profiler

## Operating Characteristics:

Frequency:	49.25 MHz	Wavelength:	6.085 m
Physical aperture:	15 600 m <sup>2</sup>	Beam Width:	2.9°
Effective aperture	13 500 m <sup>2</sup>	Azimuth angles:	45° and 135°
Power aperture product:	1.7x10 <sup>8</sup> W m <sup>2</sup>	Zenith angle:	15°
Peak Power:	250 kW	Gate Spacing:	150 m
Duty Cycle:	5%	Gate Resolution	150 m
		First Gate Height (AGL):	2009 m



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# Accuracy of the KSC 50-MHz Profiler

The KSC profiler has an RMS error near  $1 \text{ m s}^{-1}$

## *Internal Estimates:*

- Spectral Width =  $0.65 \text{ m s}^{-1}$  per beam. Resulting RSS component error =  $0.92 \text{ m s}^{-1}$
- Standard deviation of vertical speed =  $0.37 \text{ m s}^{-1}$  (about a mean of zero)

## *External Estimate:*

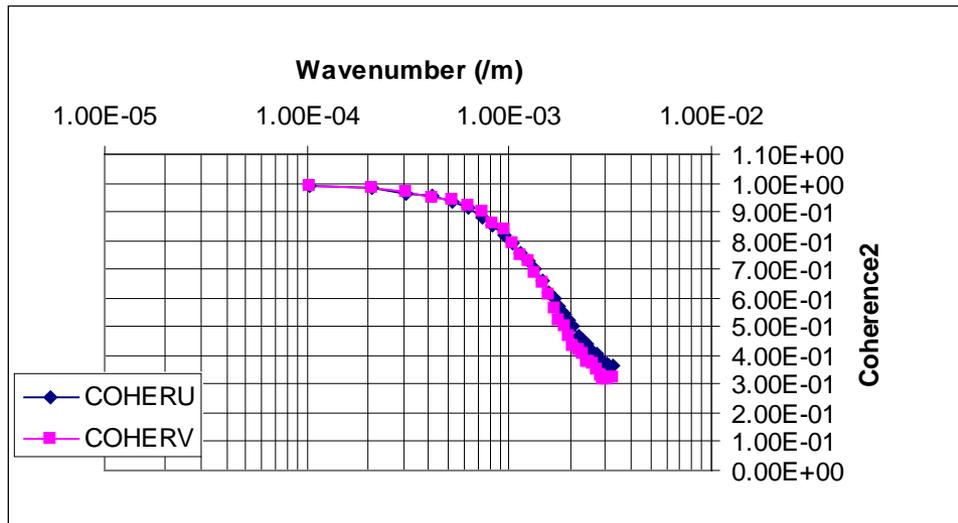
- Comparison with Jimspheres  $\sim 1 \text{ m s}^{-1}$



Jimspheres are radar-tracked balloons that provide high vertical resolution wind estimates. Jimsphere's provide the operational wind estimates prior to vehicle launch.

Schumann, R. S. et al. *J. Atmos. Oceanic Technol.*,  
16, 532-549

# Resolution of the KSC 50-MHz Profiler



KSC profiler resolves vertical scales as small as 300 to 500 m.

Details in *J. Atmos. & Oceanic Technol.* **16**, 1273-1278, 1999.

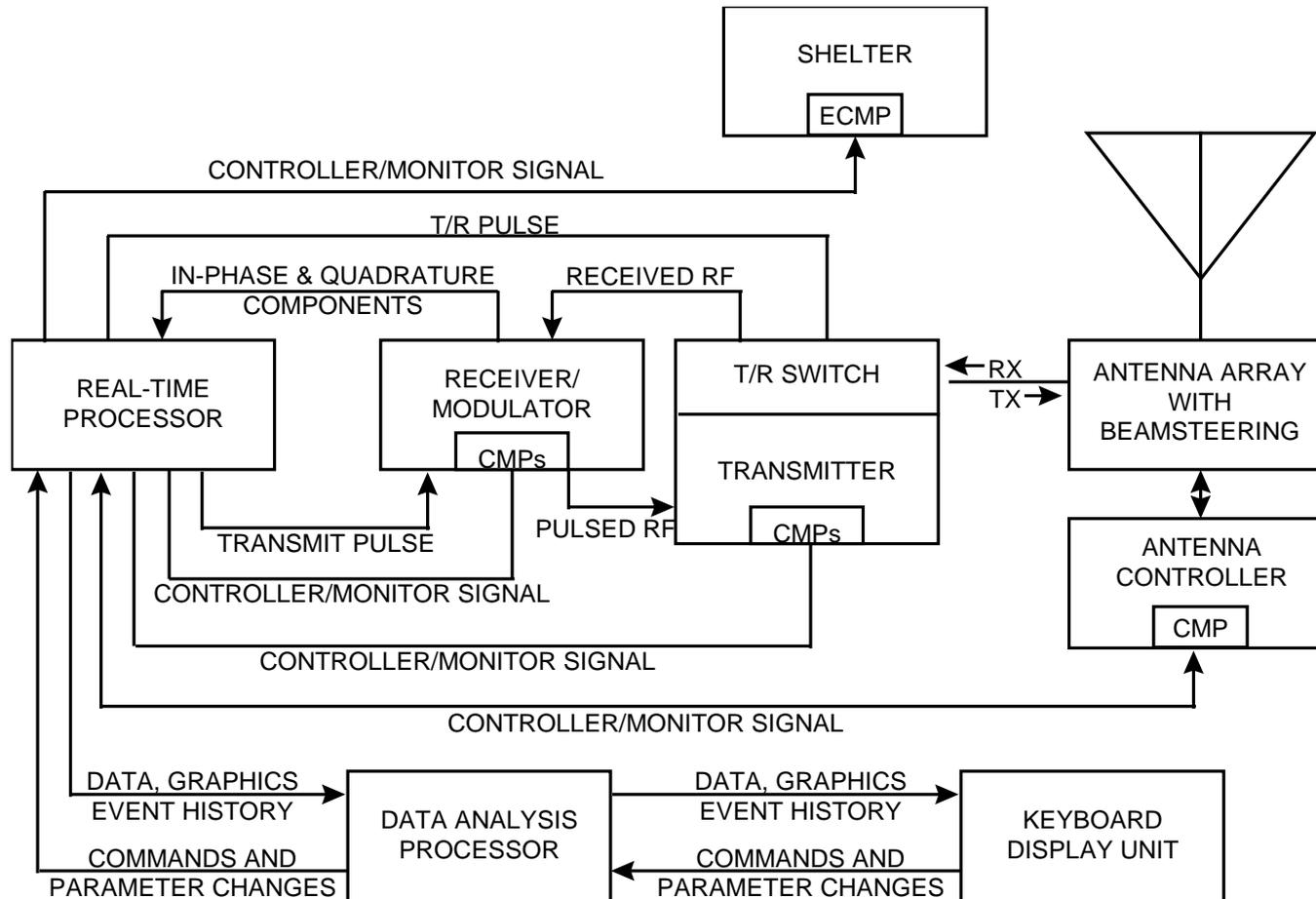
## *Methodology:*

- Coherence analysis on consecutive wind profiles
- Coherence squared threshold of 0.5
- Consecutive profiles spaced 5 minutes apart, assumed coherent.

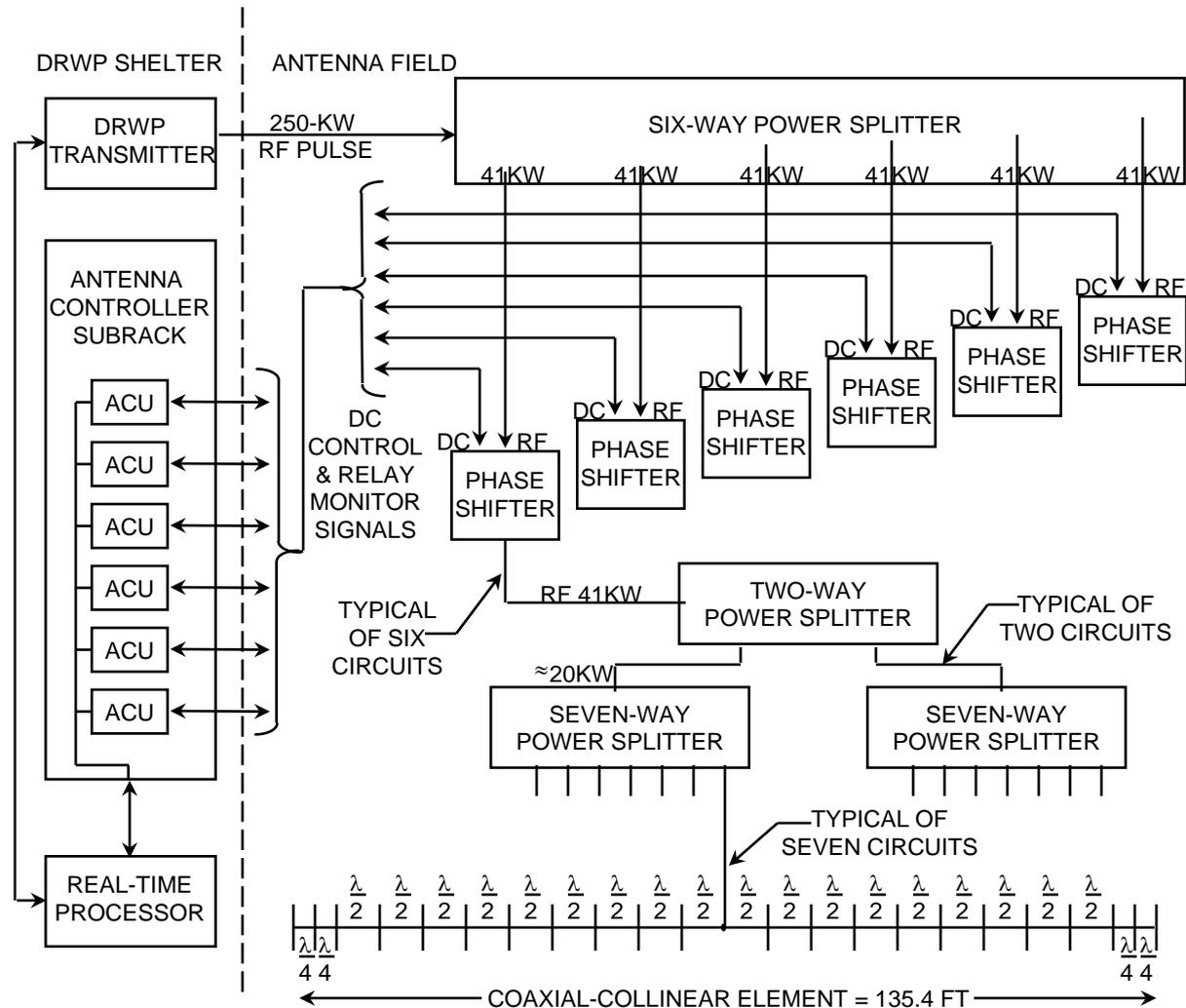
# Reliability of the KSC 50-MHz Profiler

- Instrument down time is normally less than 2%
- Two antenna outages over a ten-year period (one due to hurricane damage, one for scheduled replacement) lasted 8 weeks.
- Communications essential for day-of-launch manual quality control have not been consistently reliable. This is a failure of the communications lines, not the instrument.

# Radar Block Diagram

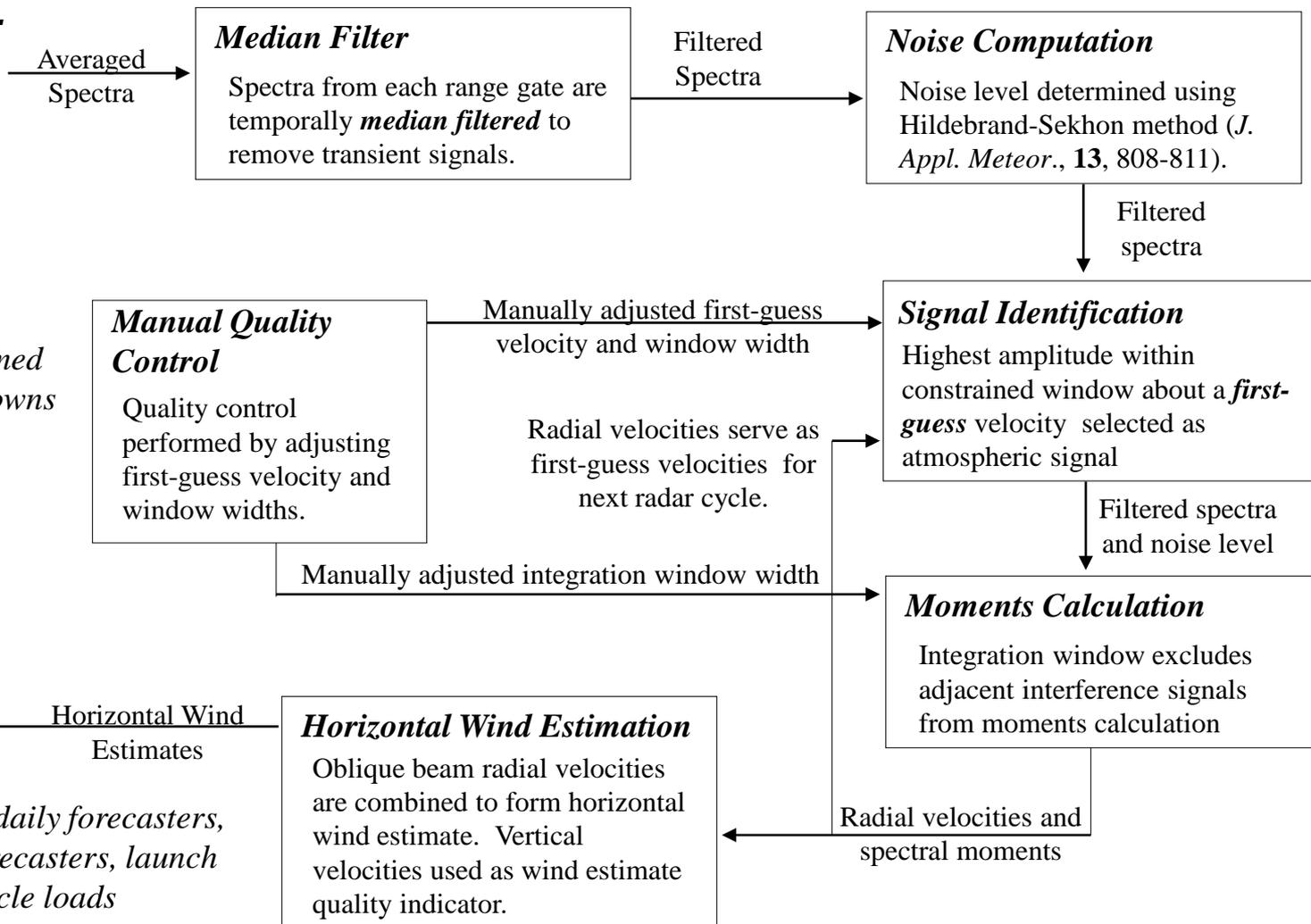


# Antenna Block Diagram



# Median Filter-First Guess Algorithm

**Profiler Real-Time Data Processor**



*Quality control performed during launch count downs or as a daily check up.*

**End Users**

*End users include daily forecasters, launch weather forecasters, launch directors, and vehicle loads evaluators.*

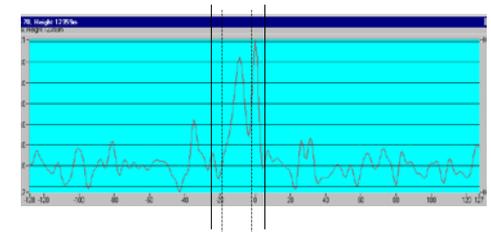
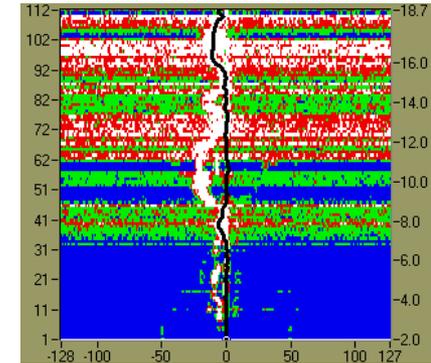
# MFFG Manual QC Methodology

## Manual QC Motivation:

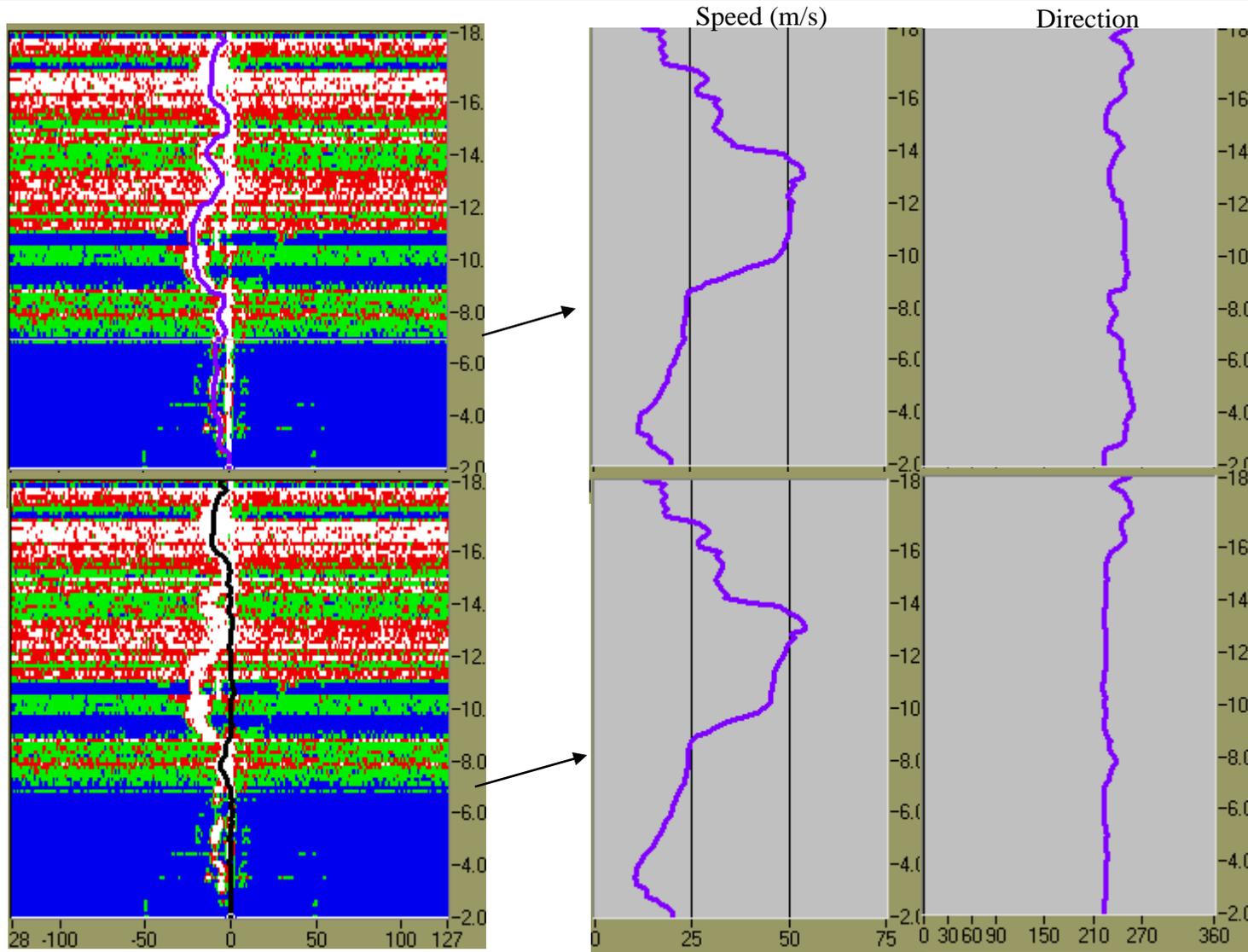
- Manual quality control is optional. The first-guess and associated windows tend to keep the radial velocity on track once they are set correctly.
- Manual quality control is provided prior to launch due to criticality of data. If discrepancies between profiler and balloons exist, they must be verified.
- For standard forecasting use, the quality control is performed once daily to ensure the profiler is on track.

## Manual QC Process:

- ① Examine each beam's radial velocity profile with respect to the median filtered spectral densities
- ② Release wind profile for distribution to data users **OR** inform end users of the altitude ranges where wind estimates are incorrect.
- ③ Modify first-guess velocity, first-guess window, or integration window as necessary for *subsequent* radar cycles' processing.
- ④ Continue with Step 1.



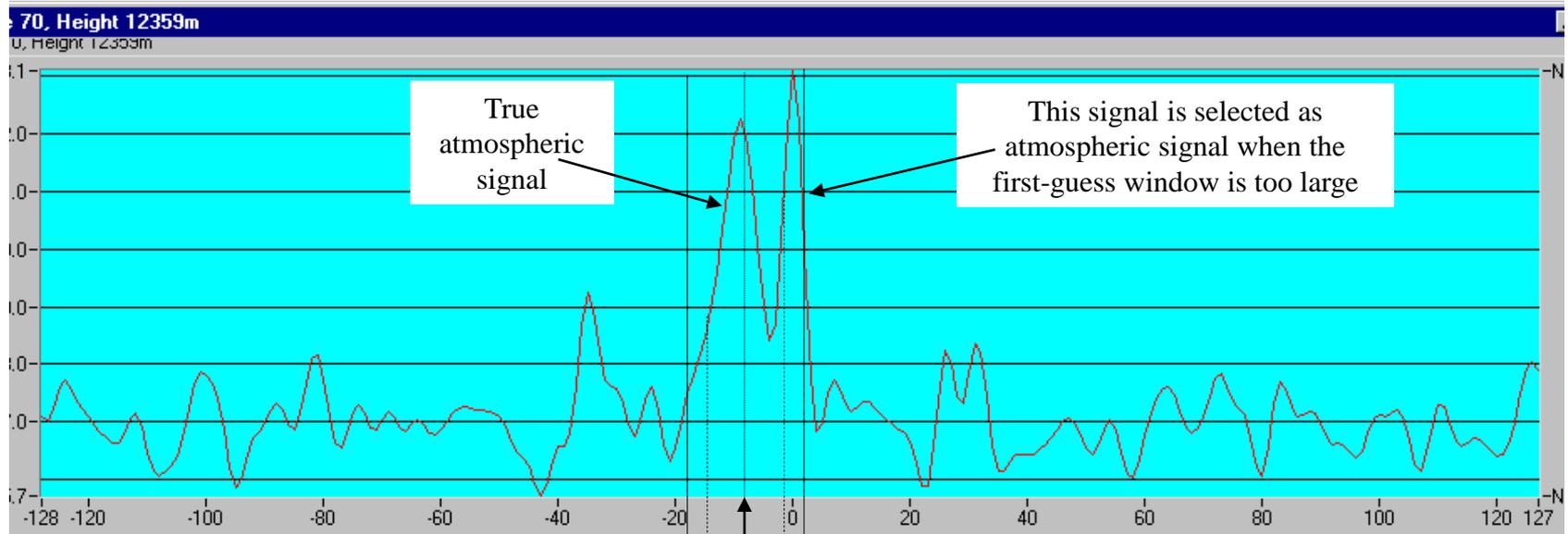
# Quality Control Effects



**QC is NOT a  
wind shear  
judgement  
call!**

# First-Guess Velocity and Window.

- First-guess velocity centers the first-guess window.
- Signal with “highest” amplitude within window selected as atmospheric signal



FG Window = 20 frequency bins

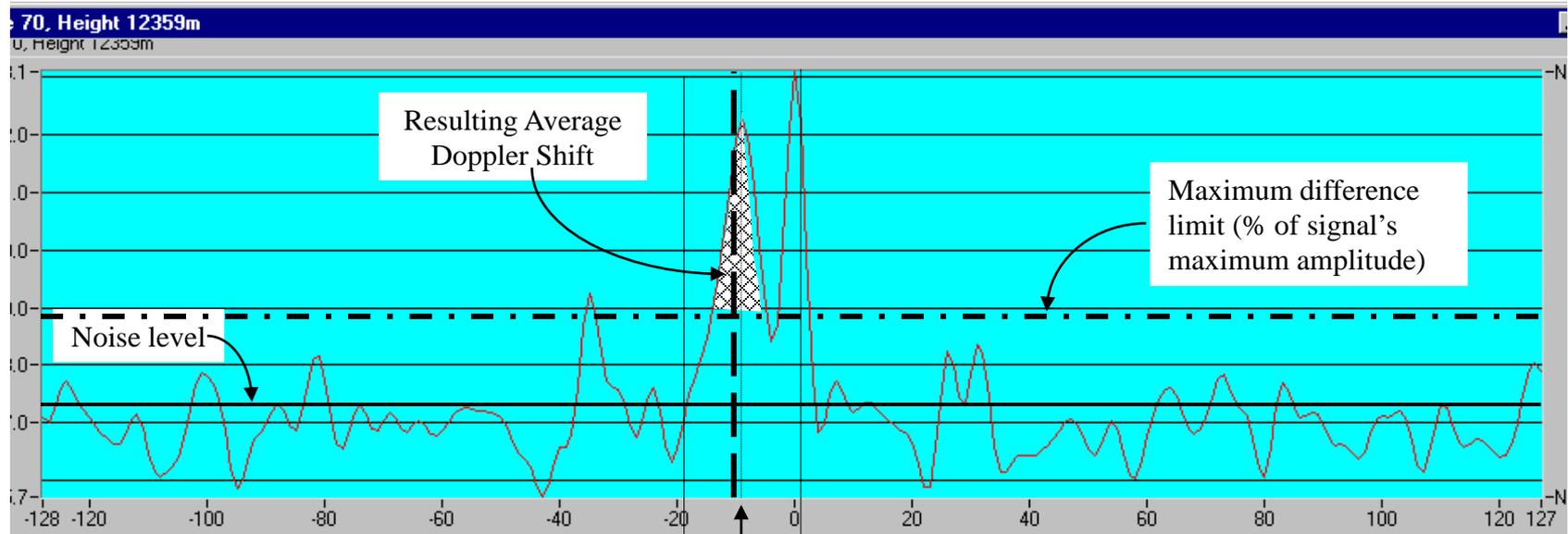
FG Window = 12 frequency bins

First-Guess  
Velocity

Operator intervention is required to exclude 0-Doppler shift signal from the atmospheric signal selection process. First-guess window must be reduced.

# Integration Window

- Signal with “highest” amplitude within first-guess window is center of integration window.
- Average Doppler Shift is weighted average of frequency shifts within integration window.



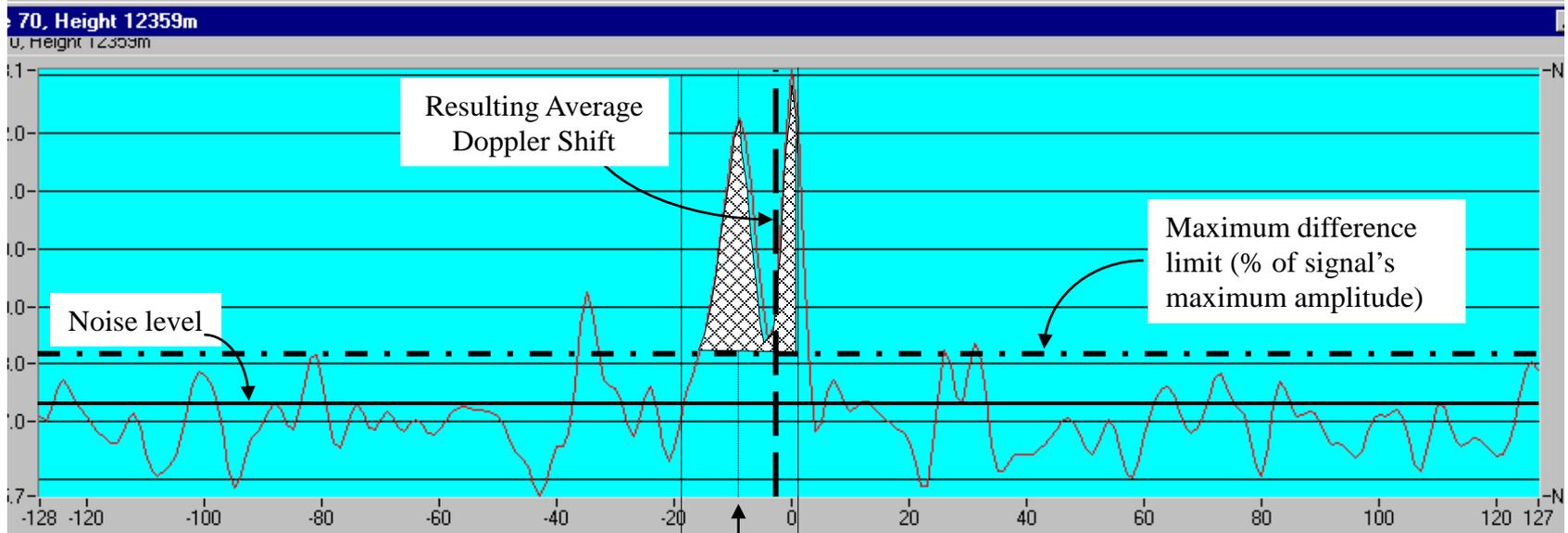
Operator-defined Integration Window = 20

Area integrated for signal power and average Doppler Shift Calculation

Center of Integration Window.

Note: Even though two signals exist within operator-defined integration window, no manual intervention required because MFFG uses most restrictive window for integration

# Integration Window



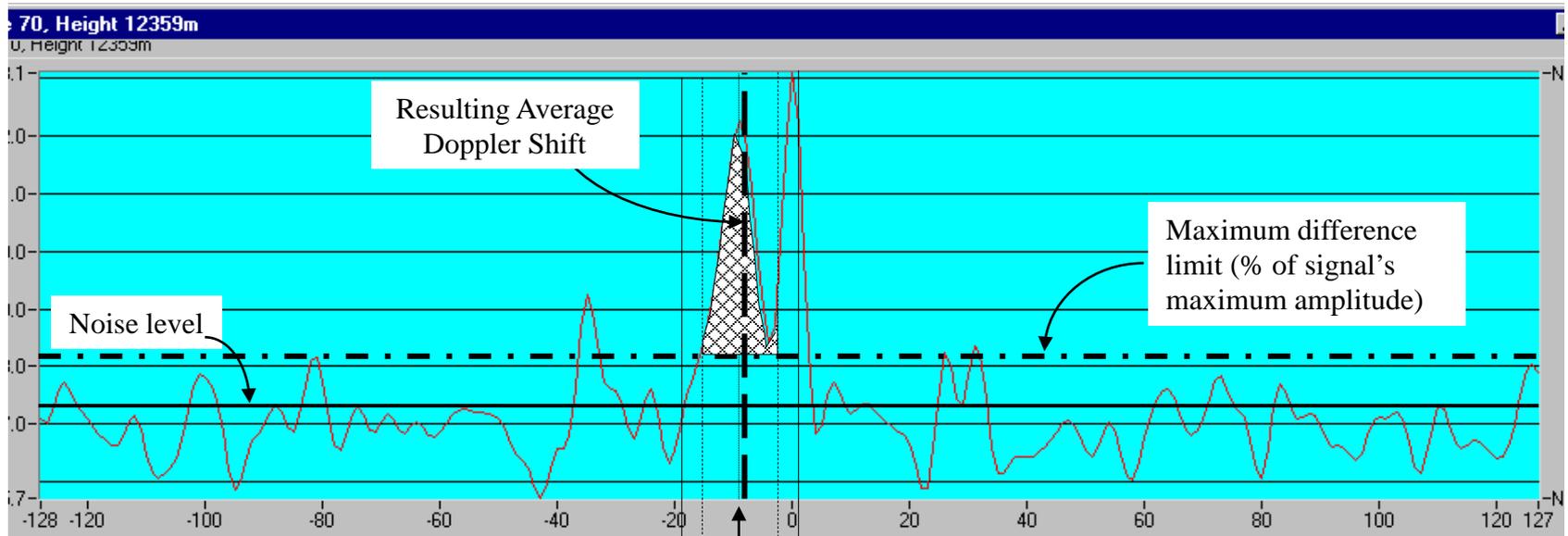
Operator-defined Integration Window = 20

 Area integrated for signal power and average Doppler Shift Calculation

Center of Integration Window.

In this case the two signals existing within operator-defined integration window are included in the integration because the maximum difference limit (not an operator parameter) falls below the local minimum between the two signals. **Integration window width intervention is required.**

# Integration Window



Operator-defined Integration Window = 20

Operator-defined Integration Window = 12

 Area integrated for signal power and average Doppler Shift Calculation

Center of Integration Window.

The narrower integration window excludes the 0-Doppler shift signal from the integration performed as part of the signal power and average Doppler shift calculation.